

SST25VF016B

16 Mbit SPI Serial Flash EOL Supplemental Information

1.0 PRODUCT DESCRIPTION

The 25 series Serial Flash family features a four-wire, SPI-compatible interface that allows for a low pin-count package which occupies less board space and ultimately lowers total system costs. The SST25VF016B devices are enhanced with improved operating frequency and even lower power consumption than the original SST25VFxxxA devices. SST25VF016B SPI serial flash memories are manufactured with proprietary, high-performance CMOS SuperFlash technology. The split-gate cell design and thick-oxide tunneling injector attain better reliability and manufacturability compared with alternate approaches.

This document provides supplemental information about the 75/80 MHz parts which are End-of-Life (EOL). Except for the information provided herein, the EOL parts behave as described in the SST25VF016B data sheet DS-20005044. See page 6 for specific part numbers.

2.0 DEVICE OPERATION

2.1 Instructions

Instructions are used to read, write (Erase and Program), and configure the SST25VF016B. The instruction bus cycles are 8 bits each for commands (Op Code), data, and addresses. Prior to executing any Byte-Program, Auto Address Increment (AAI) programming, Sector-Erase, Block-Erase, Write-Status-Register, or Chip-Erase instructions, the Write-Enable (WREN) instruction must be executed first. The complete list of instructions is provided in Table 2-1. All instructions are synchronized off a high to low transition of CE#. Inputs will be accepted on the rising edge of SCK starting with the most significant bit. CE# must be driven low before an instruction is entered and must be driven high after the last bit of the instruction has been shifted in (except for Read, Read-ID, and Read-Status-Register instructions). Any low to high transition on CE#, before receiving the last bit of an instruction bus cycle, will terminate the instruction in progress and return the device to standby mode. Instruction commands (Op Code), addresses, and data are all input from the most significant bit (MSB) first.

TABLE 2-1: DEVICE OPERATION INSTRUCTIONS

| Instruction | Description | Op Code Cycle ¹ | Address Cycle(s) ² | Dummy Cycle(s) | Data Cycle(s) | Maximum Frequency |
|---------------------------------------|--------------------------------------|---|----------------------------------|-------------------|------------------|----------------------|
| Read | Read Memory at 25 MHz | 0000 0011b (03H) | 3 | 0 | 1 to ∞ | 25 MHz |
| High-Speed Read | Read Memory at 80 MHz | 0000 1011b (0BH) 3 | | 1 | 1 to ∞ | 80 MHz |
| 4 KByte Sector- Erase ³ | Erase 4 KByte of memory array | 0010 0000b (20H) | 3 | 0 | 0 | 80 MHz |
| 32 KByte Block- Erase ⁴ | Erase 32 KByte block of memory array | 0101 0010b (52H) | 3 | 0 | 0 | 80 MHz |
| 64 KByte Block- Erase ⁵ | Erase 64 KByte block of memory array | 1101 1000b (D8H) | 3 | 0 | 0 | 80 MHz |
| Chip-Erase | Erase Full Memory Array | 0110 0000b (60H) or 1100 0111b (C7H) | 0 | 0 | 0 | 80 MHz |
| Byte-Program | To Program One Data Byte | 0000 0010b (02H) | 3 | 0 | 1 | 80 MHz |
| AAI-Word-Pro- gram ⁶ | Auto Address Increment Programming | 1010 1101b (ADH) | 3 | 0 | 2 to ∞ | 80 MHz |
| RDSR ⁷ | Read-Status-Register | 0000 0101b (05H) | 0 | 0 | 1 to ∞ | 80 MHz |
| EWSR | Enable-Write-Status-Register | 0101b 0000b (50H) | 0 | 0 | 0 | 80 MHz |
| WRSR | Write-Status-Register | 0000 0001b (01H) | 0 | 0 | 1 | 80 MHz |

TABLE 2-1: DEVICE OPERATION INSTRUCTIONS

| Instruction | Description | Op Code Cycle ¹ | Address Cycle(s) ² | Dummy Cycle(s) | Data Cycle(s) | Maximum Frequency |
|-------------------|--|---|----------------------------------|-------------------|------------------|----------------------|
| WREN | Write-Enable | 0000 0110b (06H) | 0 | 0 | 0 | 80 MHz |
| WRDI | Write-Disable | 0000 0100b (04H) | 0 | 0 | 0 | 80 MHz |
| RDID ⁸ | Read-ID | 1001 0000b (90H) or 1010 1011b (ABH) | 3 | 0 | 1 to ∞ | 80 MHz |
| JEDEC-ID | JEDEC ID read | 1001 1111b (9FH) | 0 | 0 | 3 to ∞ | 80 MHz |
| EBSY | Enable SO to output RY/BY# status during AAI program- ming | 0111 0000b (70H) | 0 | 0 | 0 | 80 MHz |
| DBSY | Disable SO as RY/BY# status during AAI program- ming | 1000 0000b (80H) | 0 | 0 | 0 | 80 MHz |

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- 1. One bus cycle is eight clock periods.
- 2. Address bits above the most significant bit of each density can be V_{II} or V_{IH} .
- 3. 4KByte Sector Erase addresses: use A_{MS} - A_{12} , remaining addresses are don't care but must be set either at V_{IL} or V_{IH} .
- 4. 32KByte Block Erase addresses: use A_{MS} - A_{15} , remaining addresses are don't care but must be set either at V_{IL} or V_{IH} .
- 5. 64KByte Block Erase addresses: use A_{MS}-A₁₆, remaining addresses are don't care but must be set either at V_{IL} or V_{IH}.
- 6. To continue programming to the next sequential address location, enter the 8-bit command, ADH, followed by 2 bytes of data to be programmed. Data Byte 0 will be programmed into the initial address [A₂₃-A₁] with A₀=0, Data Byte 1 will be programmed into the initial address [A₂₃-A₁] with A₀=1.
- 7. The Read-Status-Register is continuous with ongoing clock cycles until terminated by a low to high transition on CE#.
- 8. Manufacturer's ID is read with A₀=0, and Device ID is read with A₀=1. All other address bits are 00H. The Manufacturer's ID and device ID output stream is continuous until terminated by a low-to-high transition on CE#.

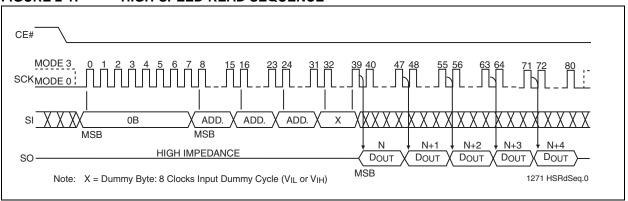
2.1.1 HIGH-SPEED-READ (80 MHZ)

The High-Speed-Read instruction supporting up to 80 MHz Read is initiated by executing an 8-bit command, 0BH, followed by address bits $[A_{23}$ - $A_0]$ and a dummy byte. CE# must remain active low for the duration of the High-Speed-Read cycle. See Figure 2-1 for the High-Speed-Read sequence.

Following a dummy cycle, the High-Speed-Read instruction outputs the data starting from the specified address location. The data output stream is continuous

through all addresses until terminated by a low to high transition on CE#. The internal address pointer will automatically increment until the highest memory address is reached. Once the highest memory address is reached, the address pointer will automatically increment to the beginning (wrap-around) of the address space. Once the data from address location 1FFFFFH has been read, the next output will be from address location 000000H.

FIGURE 2-1: HIGH-SPEED-READ SEQUENCE



3.0 **ELECTRICAL SPECIFICATIONS**

TABLE 3-1: DC OPERATING CHARACTERISTICS

| | | L | imits | | |
|-------------------|---------------------------|----------------------|-------|-------|---|
| Symbol | Parameter | Min | Max | Units | Test Conditions |
| I _{DDR} | Read Current | | 10 | mA | CE#=0.1 V _{DD} /0.9 V _{DD} @25 MHz, SO=open |
| I _{DDR2} | Read Current | | 15 | mA | CE#=0.1 V _{DD} /0.9 V _{DD} @50 MHz, SO=open |
| I _{DDR3} | Read Current | | 20 | mA | CE#=0.1 V _{DD} /0.9 V _{DD} @80 MHz, SO=open |
| I _{DDW} | Program and Erase Current | | 30 | mA | CE#=V _{DD} |
| I _{SB} | Standby Current | | 20 | μΑ | CE#=V _{DD} , V _{IN} =V _{DD} or V _{SS} |
| ILI | Input Leakage Current | | 1 | μΑ | V_{IN} =GND to V_{DD} , V_{DD} = V_{DD} Max |
| I_{LO} | Output Leakage Current | | 1 | μΑ | V_{OUT} =GND to V_{DD} , V_{DD} = V_{DD} Max |
| V_{IL} | Input Low Voltage | | 0.8 | V | $V_{DD}=V_{DD}$ Min |
| V _{IH} | Input High Voltage | 0.7 V _{DD} | | V | V _{DD} =V _{DD} Max |
| V _{OL} | Output Low Voltage | | 0.2 | V | I _{OL} =100 μA, V _{DD} =V _{DD} Min |
| V_{OL2} | Output Low Voltage | | 0.4 | V | I _{OL} =1.6 mA, V _{DD} =V _{DD} Min |
| V_{OH} | Output High Voltage | V _{DD} -0.2 | | V | I _{OH} =-100 μA, V _{DD} =V _{DD} Min |

TABLE 3-2: AC OPERATING CHARACTERISTICS

| | | 80 | | |
|--------------------------------|------------------------------------|-----|-----|-------|
| Symbol | Parameter | Min | Max | Units |
| F _{CLK} ¹ | Serial Clock Frequency | | 80 | MHz |
| T _{SCKH} | Serial Clock High Time | 6 | | ns |
| T _{SCKI} | Serial Clock Low Time | 6 | | ns |
| T _{SCKR} ² | Serial Clock Rise Time (Slew Rate) | 0.1 | | V/ns |
| T _{SCKF} | Serial Clock Fall Time (Slew Rate) | 0.1 | | V/ns |
| T_{CFS}^3 | CE# Active Setup Time | 5 | | ns |
| T _{CFH} ³ | CE# Active Hold Time | 5 | | ns |
| T _{CHS} ³ | CE# Not Active Setup Time | 5 | | ns |
| T _{CHH} ³ | CE# Not Active Hold Time | 5 | | ns |
| T _{CPH} | CE# High Time | 50 | | ns |
| T _{CHZ} | CE# High to High-Z Output | | 7 | ns |
| T _{CLZ} | SCK Low to Low-Z Output | 0 | | ns |
| T _{DS} | Data In Setup Time | 2 | | ns |
| T _{DH} | Data In Hold Time | 4 | | ns |
| T _{HLS} | HOLD# Low Setup Time | 5 | | ns |
| T _{HHS} | HOLD# High Setup Time | 5 | | ns |
| T _{HLH} | HOLD# Low Hold Time | 5 | | ns |
| T _{HHH} | HOLD# High Hold Time | 5 | | ns |
| T _{HZ} | HOLD# Low to High-Z Output | | 7 | ns |
| T_{LZ} | HOLD# High to Low-Z Output | | 7 | ns |
| T _{OH} | Output Hold from SCK Change | 0 | | ns |
| T _V | Output Valid from SCK | | 6 | ns |
| T _{SE} | Sector-Erase | | 25 | ms |
| T _{BE} | Block-Erase | | 25 | ms |
| T _{SCE} | Chip-Erase | | 50 | ms |
| T _{BP} | Byte-Program | | 10 | μs |

^{1.} Maximum clock frequency for Read Instruction, 03H, is 25 MHz 2. Maximum Rise and Fall time may be limited by T_{SCKH} and T_{SCKL} requirements 3. Relative to SCK.

SST25VF016B

TABLE 3-3: REVISION HISTORY

| Revision | Description | Date |
|----------|-----------------------------------|----------|
| Α | Initial release of EOL data sheet | Apr 2015 |

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| PART NO Device | Operating Frequency | - XX - XX - X Minimum Temp Package Tape/Reel Endurance Range Indicator | Valid Combinations: SST25VF016B-75-4I-S2AE SST25VF016B-75-4I-S2AE-T SST25VF016B-75-4I-QAE SST25VF016B-75-4I-QAE-T |
|-------------------------|---------------------|--|---|
| Device: | SST25VF016B | = 16 Mbit, 2.7-3.6V, SPI Flash Memory | 33123VI 010D-73-4FQAL-1 |
| Operating Frequency: | 75 | = 75 MHz (80 MHz) | |
| Minimum Endurance | 4 | = 10,000 cycles | |
| Temperature: | I C | = -40°C to +85°C = 0°C to +70°C | |
| Package: | QAE S2AE | = WSON (6mm x 5mm Body), 8-lead = SOIC (200 mil Body), 8-lead | |
| Tape and Reel Flag: | Т | = Tape and Reel | |

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ISBN:978-1-63277-221-3

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